

# Efficient near-ML Decoding via Statistical Pruning <sup>1</sup>

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**Abstract** — Maximum-likelihood (ML) decoding often reduces to finding the closest (skewed) lattice point in  $N$ -dimensions to a given point  $x \in \mathcal{C}^N$ . Sphere decoding is an algorithm that does this. We modify the sphere decoder to reduce the computational complexity of decoding while maintaining near-ML performance.

## I. SYSTEM MODEL

We assume a discrete-time, block-fading, multiple-antenna channel model with  $N$  transmit and  $N$  receive antennas, where the channel is known to the receiver. If  $\mathcal{S}$  is the signal space, the transmitted signal  $\tilde{s} \in \mathcal{S}^{N \times 1}$  and the received signal  $x \in \mathcal{C}^{N \times 1}$  are related by  $x = \sigma_h H \tilde{s} + v$  where  $H \in \mathcal{C}^{N \times N}$  is the known channel matrix and  $v \in \mathcal{C}^{N \times 1}$  is the additive noise vector. Both are comprised of i.i.d. complex-Gaussian entries  $\mathcal{CN}(0, 1)$ .  $\sigma_h$  determines the SNR. Under these conditions the ML criterion requires us to find  $s \in \mathcal{S}^{N \times 1}$  that minimizes  $\|x - Hs\|^2$ .

## II. SPHERE DECODER

The sphere decoder finds lattice points in a hypersphere of radius  $r$  centered at  $x$ , i.e., it finds all  $s \in \mathcal{S}^{N \times 1}$  that satisfy  $r^2 \geq \|x - Hs\|^2$ . For this, we decompose  $H$  as  $H = QR$  where  $Q$  is unitary and  $R$  is upper triangular with positive diagonal. (Both are  $N \times N$ .) Then  $\|x - Hs\|^2 = \|Q^*x - Rs\|^2$ . Define  $y' = Q^*x - Rs$  and  $\lambda_i = |y'_{N-i+1}|^2$  for  $i = 1, 2, \dots, N$ . We need to solve  $\lambda_1 + \lambda_2 + \dots + \lambda_N \leq r^2$ . This is done by solving successively for  $\lambda_1 \leq r^2$ ;  $\lambda_1 + \lambda_2 \leq r^2$ ;  $\dots$ ;  $\lambda_1 + \lambda_2 + \dots + \lambda_N \leq r^2$ . This can be done because the first condition gives an interval for  $s_N$ , whereas for any pre-determined  $s_N, \dots, s_{N-i+2}$ , the  $i$ -th condition gives an interval for  $s_{N-i+1}$ . While the sphere decoder avoids exhaustive search it does incur very high computational complexities for very large  $N$  [1]. This happens because to have a high probability of finding at least one point in the hypersphere,  $r$  has to be proportional to  $N$  and a very large fraction of the points is retained in the early dimensions.

## III. STATISTICAL PRUNING

To prune the search space right from the smaller dimensions, we modify the sphere decoder. We determine a schedule of radii  $r_1 \leq r_2 \leq \dots \leq r_N$  and solve for  $\lambda_1 \leq r_1^2$ ;  $\lambda_1 + \lambda_2 \leq r_2^2$ ;  $\dots$ ;  $\lambda_1 + \lambda_2 + \dots + \lambda_N \leq r_N^2$ . Call this region  $\mathcal{D}$ . Since  $\mathcal{D}$  is not hyperspherical, this is not exact ML decoding. If  $\epsilon$  is the probability that the transmitted vector is not in  $\mathcal{D}$ , a loose upper bound on the probability of error is  $P_e \leq P_e^{ML} + \epsilon$ . The quantity  $\epsilon$  can be determined exactly in terms of the  $r_i$ s and so the  $r_i$ s can be chosen to make  $\epsilon$  as small as desired to ensure near-ML performance.

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## IV. RESULTS

The expected computational complexity  $C$  is given by  $\sum_{k=1}^N (\text{expected \# of points in } \mathcal{D}_k) \cdot (\text{flops/point})$  where  $\mathcal{D}_k$  is the restriction of  $\mathcal{D}$  to the  $k$ -th dimension. The expected # of points in  $\mathcal{D}_k$  is given by  $\sum_{s^k \in \mathcal{S}^{k \times 1}} P(s^k \in \mathcal{D}_k)$  and flops/point =  $8k + 32$  for the  $k$ -th dimension. An upper bound on  $P(s^k \in \mathcal{D}_k)$  leads to

$$C \leq \sum_{k=1}^N (8k + 32) \sum_{l=0}^{2k} \binom{2k}{l} \Gamma\left(\frac{r_k^2}{1 + \sigma_h^2 l}, k\right) \quad (1)$$

for QPSK constellations. Here  $\Gamma(x, a) = \int_0^x \frac{e^{-t}}{\Gamma(a)} t^{a-1} dt$ . An approximation to  $P(s^k \in \mathcal{D}_k)$  leads to

$$C \approx \sum_{k=1}^N (8k + 32) \sum_{s^k \in \mathcal{S}^{k \times 1}} \prod_{j=1}^k \min(1, \frac{X_k}{2(1 + \sigma_h^2 \|s^j - \tilde{s}^j\|^2)}) \quad (2)$$

where the  $X_i$ s depend on  $s^i - \tilde{s}^i$  and can be obtained recursively. This is computed efficiently with Monte Carlo simulations.

## V. SIMULATIONS

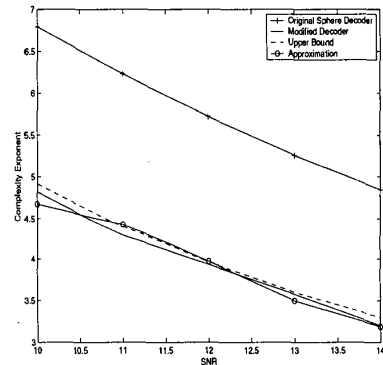


Figure 1: Complexity Exponent for  $N=50$  with QPSK

Fig. (1) shows the complexity exponent ( $\log C / \log N$ ) for  $N = 50$  with the sphere decoder as well as the modified algorithm. The approximation and the upper bound are also plotted. A linear schedule of radii  $r_i^2 = (\delta \log N + i)$  with  $\delta$  chosen to make  $\epsilon = 0.01$  was used. A computational savings of  $50^2 = 2500$  is observed.

## VI. CONCLUSIONS

The algorithm reduces decoding complexity by exploiting the statistics of the problem. Performance can be made arbitrarily close to ML by choice of  $\epsilon$ .

## REFERENCES

- [1] B. Hassibi and H. Vikalo, "The complexity of sphere decoding. pt. I Expected Complexity," *Submitted to IEEE Trans. Sig. Proc.*, 2003